

# ICCRI 2022

2022 5TH INTERNATIONAL CONFERENCE ON  
CONTROL, ROBOTICS AND INFORMATICS

Danang, Vietnam ✧ April 2-4, 2022



## Paper Publication

Submitted papers will be peer reviewed by conference committees, and accepted papers after registration and presentation will be published in **International Conference Proceedings**, which will be submitted to **EI Compendex**, **Scopus**, etc for indexing.

Extended papers will be recommended to **International Journal of Mechanical Engineering and Robotics Research** for publication as a special issue, which will be indexed by **Scopus**, Index Copernicus, ProQuest, UDL, Google Scholar, Open J-Gate etc.

## CALL FOR PAPERS

### Control and Robotics

Adaptive control, Robust control, Process control, Complex systems, Co-operative control, Intelligent systems, Modeling and identification, Robot control, Mobile robotics, Mobile sensor networks, Micro robots and micro-manipulation, Visual servoing, Search, rescue and field robotics, Robot sensing and data fusion, Localization, navigation and mapping, Dexterous manipulation, Medical robots and bio-robotics, Human centered systems, Space and underwater robots.

### Informatics

Intelligent control systems and optimization robotics and automation signal processing, Sensors, Systems modelling and control industrial informatics.

## Important Dates

Submission Deadline: November 15, 2021  
Notification Date: December 10, 2021  
Registration Deadline: December 30, 2021  
Conference Dates: April 2-4, 2022

## Submission

Please submit your full paper/abstract via Electronic Submission System:  
<http://confsys.iconf.org/conference/iccri2022>  
Or via the email: [iccri@iap.org](mailto:iccri@iap.org)

Conference Secretary: Mia Hu

Tel.: +86-28-86512185

E-mail: [iccri@iap.org](mailto:iccri@iap.org)

Website: <http://www.iccri.org/>



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## SPEAKERS



**Prof. Rajender Singh Chhillar**  
Maharshi Dayanand University, Rohtak, India



**Assoc. Prof. Dr. Nguyen Chi Ngon**  
College of Engineering Technology, Can Tho University, Vietnam

To be added...

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